

Real Oscillators

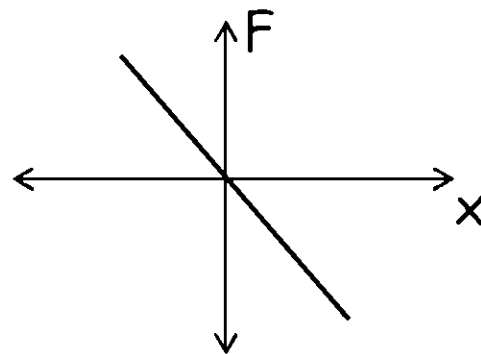
... constant forces \rightarrow integrate EOM \rightarrow parabolic trajectories.

... linear restoring force \rightarrow guess EOM solution \rightarrow SHM

... nonlinear restoring forces \rightarrow ?

linear spring

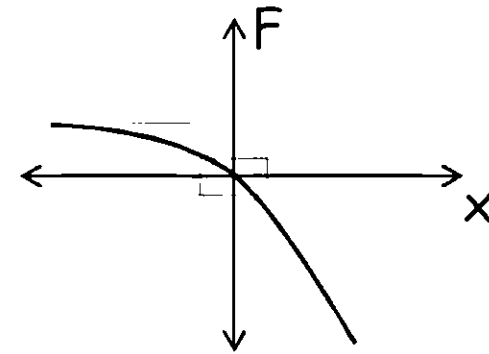
$$F = -kx$$



$$-kx = m\ddot{x}$$

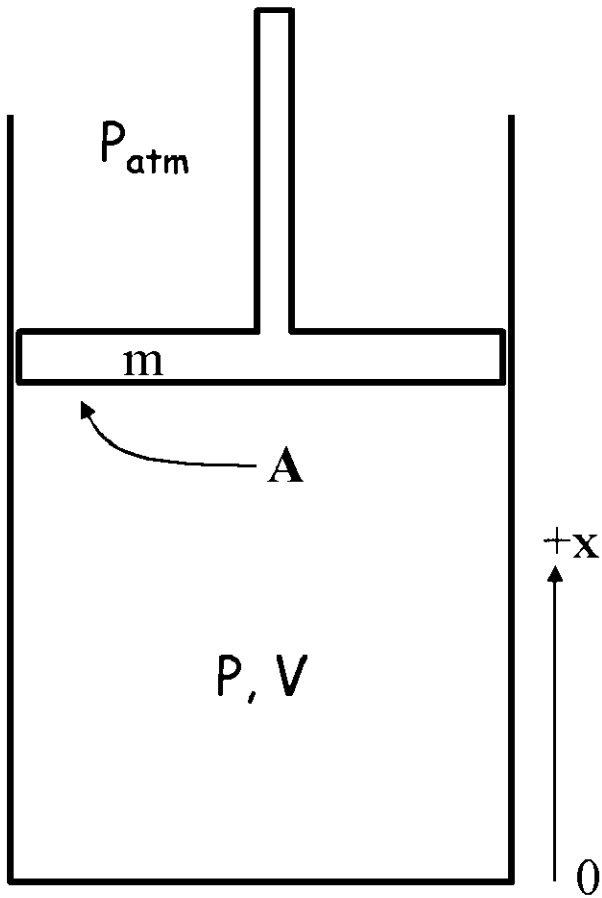
nonlinear spring?

$$F = c(1 - e^x)$$



$$c(1 - e^x) = m\ddot{x}$$

The spring of air :



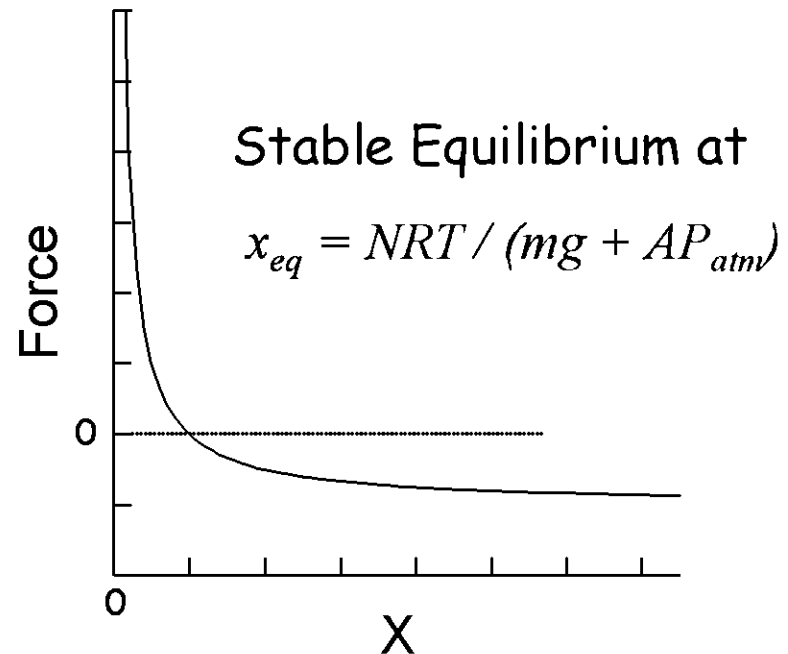
$$\Sigma F = -mg - AP_{atm} + AP = m\ddot{x}$$

use Ideal Gas Law: $PV = NRT$

$$-mg - AP_{atm} + A \frac{NRT}{V} = m\ddot{x}$$

chamber volume: $V = Ax$

$$\boxed{-mg - AP_{atm} + \frac{NRT}{x} = m\ddot{x}} \quad \text{EOM}$$

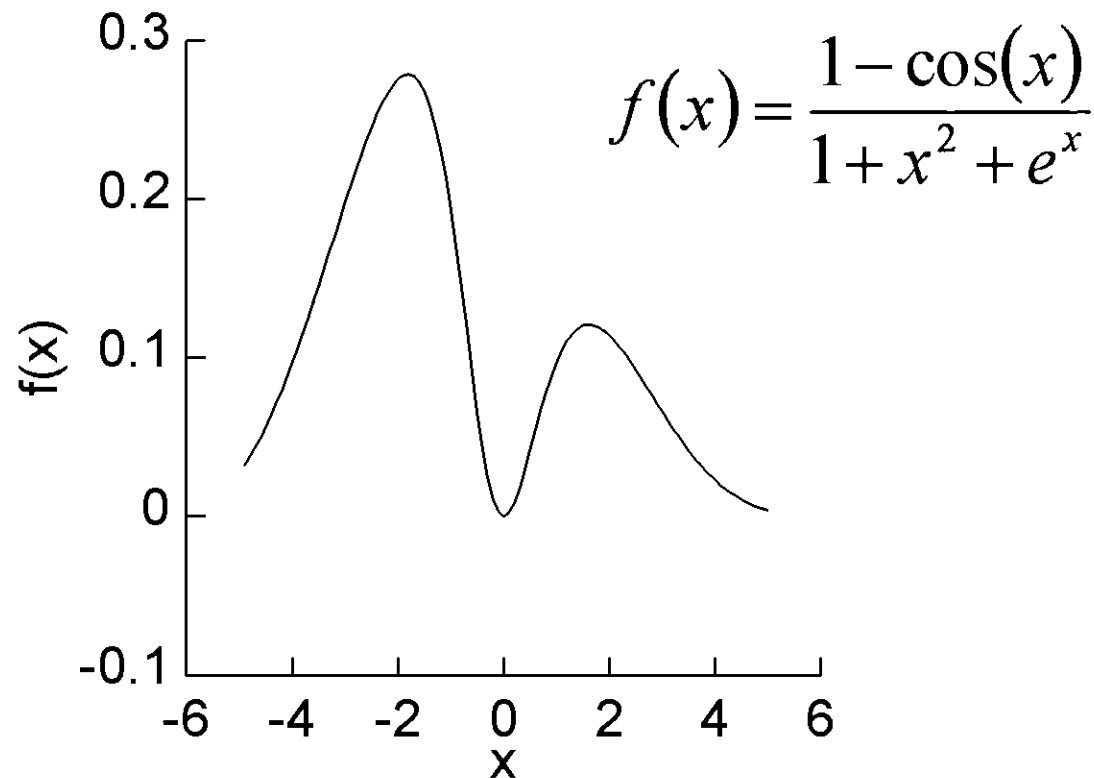


Taylor Series Expansions:

$$f(x) = \sum_{n=0}^{\infty} \frac{\frac{d^n f}{dx^n}(a)}{n!} (x-a)^n$$

Turns a function into a polynomial near $x = a$

Example:



Expand NRT/x around x_{eq} :

$$\left[-mg - AP_{atm} + \frac{NRT}{x_{eq}} - \frac{NRT}{x_{eq}^2} (x - x_{eq}) + \frac{NRT}{x_{eq}^3} (x - x_{eq})^2 - \dots \right] = m\ddot{x}$$

$$\left[0 - \frac{NRT}{x_{eq}^2} (x - x_{eq}) + \frac{NRT}{x_{eq}^3} (x - x_{eq})^2 - \dots \right] = m\ddot{x}$$

Is it safe to linearize it? Better check a unitless ratio. How about:

$$\left(\frac{x - x_{eq}}{x_{eq}} \right)$$

(Yes, excellent choice Dr. Hafner!)

$$\frac{NRT}{x_{eq}} \left[0 - \left(\frac{x - x_{eq}}{x_{eq}} \right) + \left(\frac{x - x_{eq}}{x_{eq}} \right)^2 - \dots \right] = m\ddot{x}$$

Displacement 5% of x_{eq} : 0 .05 .0025

$$-\frac{NRT}{2x_{eq}} (x - x_{eq}) \approx m\ddot{x}$$

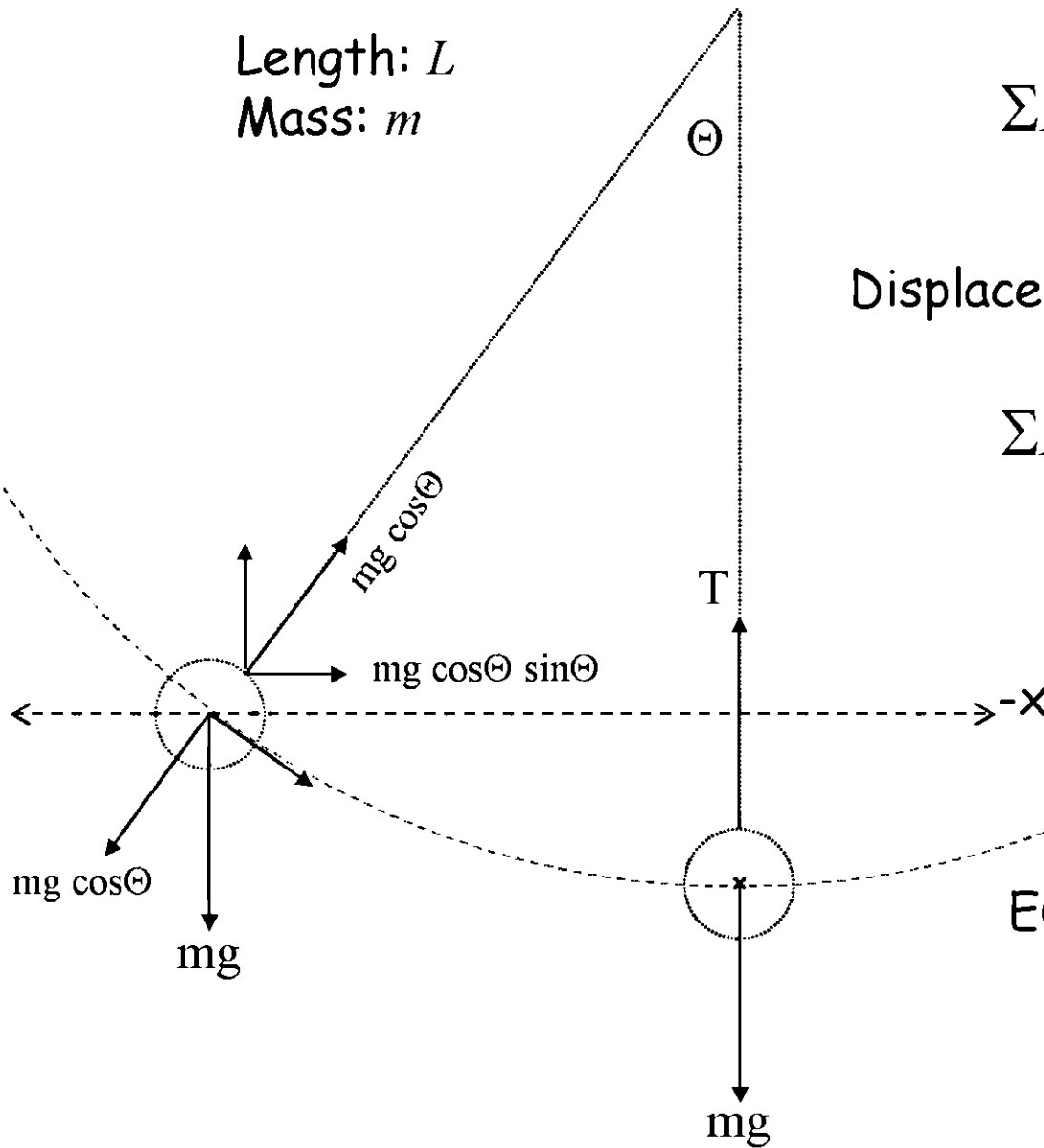
Perhaps you would prefer....

$$-\frac{NRT}{m x_{eq}} (x - x_{eq}) \approx \ddot{(x - x_{eq})}$$

$$\text{SHM with } \omega_o = \frac{\sqrt{NRT/m}}{x_{eq}}$$

Simple Pendulum:

Length: L
Mass: m



Stable Equilibrium:

$$\Sigma F_x = 0$$

$$\Sigma F_y = T - mg = 0$$

Displace by Θ :

$$\Sigma F_x = -mg \cos(\Theta) \sin(\Theta)$$

$$= -mg \frac{\sqrt{L^2 - x^2}}{L} \frac{x}{L}$$

$$\text{EOM: } -mg \frac{\sqrt{L^2 - x^2}}{L} \frac{x}{L} = m\ddot{x}$$

Expand it!

$$-\frac{g}{L^2} x \sqrt{L^2 - x^2} = \ddot{x}$$

Derivatives:

$$f = x \sqrt{L^2 - x^2}$$

$$f' = \sqrt{L^2 - x^2} - x^2 (L^2 - x^2)^{-\frac{1}{2}}$$

$$f'' = -3x (L^2 - x^2)^{-\frac{1}{2}} - x^3 (L^2 - x^2)^{-\frac{3}{2}}$$

$$f''' = -3 (L^2 - x^2)^{-\frac{1}{2}} - 6x^2 (L^2 - x^2)^{-\frac{3}{2}} - 3x^4 (L^2 - x^2)^{-\frac{5}{2}}$$

$$-\frac{g}{L^2} \left[0 + Lx + 0 - \frac{3}{6L} x^3 \dots \right] = \ddot{x}$$

Now express as a unitless ratio of the dependent variable and some parameter of the system:

$$-g \left[0 + \left(\frac{x}{L} \right) + 0 - \frac{1}{2} \left(\frac{x}{L} \right)^3 \dots \right] = \ddot{x}$$

Displacement 5% of length: 0 .05 0 .0000625 ...

$$-\frac{g}{L} x \approx \ddot{x} \quad \text{SHM with } \omega_o = \sqrt{\frac{g}{L}}$$

The world is not linear. However, one can use a Taylor expansion to linearize an EOM by assuming only small perturbations around a point of stable equilibrium (which may not be the origin).