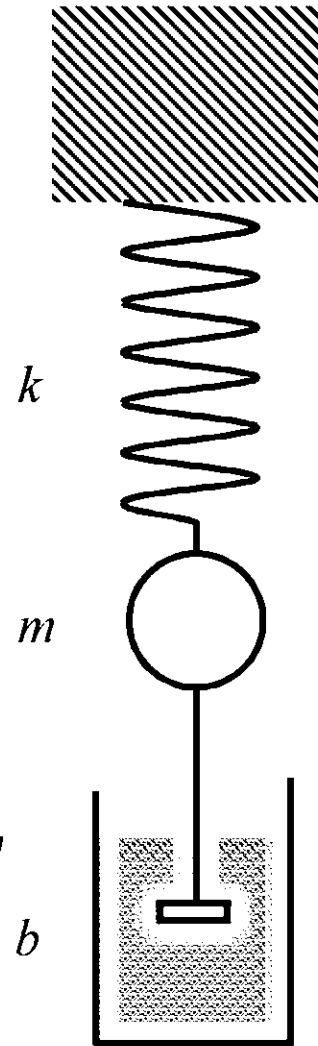


Damped SHM



"Damping Constant"
(kg/s)

$$\sum F = -b\dot{x} - kx = m\ddot{x}$$

$$\omega_o = \sqrt{k/m} \quad \gamma = b/m$$

"Natural Frequency" (rad/s) "Damping Parameter" (s⁻¹)

$$\ddot{x} + \gamma \dot{x} + \omega_o^2 x = 0$$

EOM: damped oscillator

Guess a complex solution: $z(t) = Ae^{j(pt+\phi)}$

$$j^2 p^2 Ae^{j(pt+\phi)} + \gamma p Ae^{j(pt+\phi)} + \omega_o^2 Ae^{j(pt+\phi)} = 0$$

$$Ae^{j(pt+\phi)}(-p^2 + \gamma p + \omega_o^2) = 0$$

$A = 0$

"trivial solution"

$$-p^2 + \gamma p + \omega_o^2 = 0$$

Actually 2 equations:

Real = 0

$$-p^2 + \omega_o^2 = 0$$

$$p = \omega_o$$

Imaginary = 0

$$\gamma p = 0$$

$$\gamma = 0$$

... also trivial !

Try a complex frequency: $z(t) = Ae^{j((n+js)t+\phi)}$

$$-(n+js)^2 + \gamma j(n+js) + \omega_o^2 = 0$$

$$-n^2 - 2jns + s^2 + \gamma jn - \gamma s + \omega_o^2 = 0$$

Real

$$-n^2 + s^2 - \gamma s + \omega_o^2 = 0$$

$$-n^2 + \frac{\gamma^2}{4} - \frac{\gamma^2}{2} + \omega_o^2 = 0$$

$$n^2 = \omega_o^2 - \frac{\gamma^2}{4}$$

Imaginary

$$-2jns + \gamma jn = 0$$

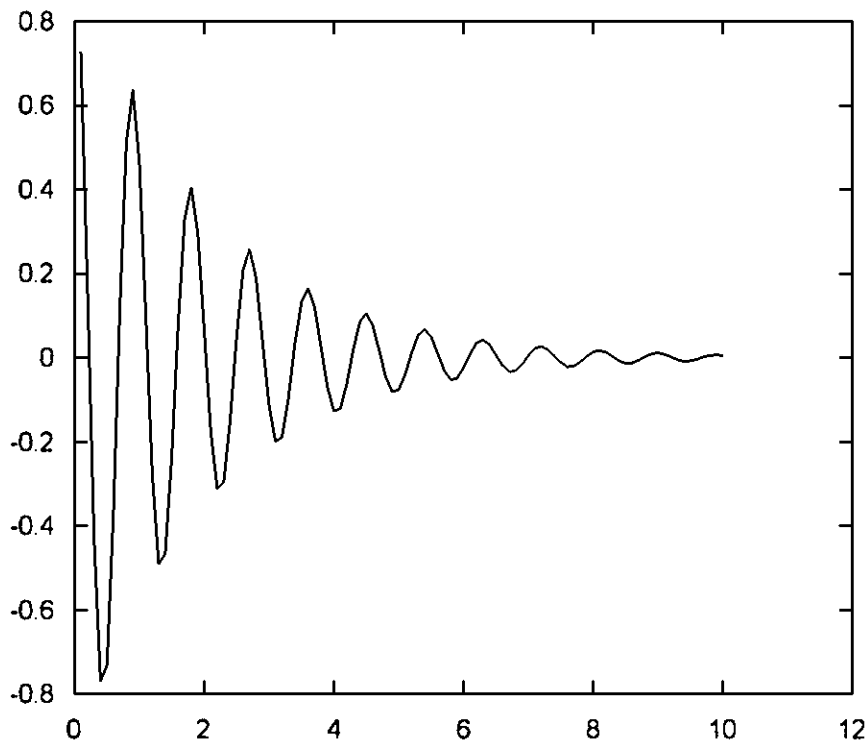
$$s = \frac{\gamma}{2}$$

A, ϕ are free constants.

$$z(t) = Ae^{j\left(\left(\sqrt{\omega_o^2 - \frac{\gamma^2}{4}} + j\frac{\gamma}{2}\right)t + \phi\right)}$$

$$z(t) = Ae^{-\frac{\gamma}{2}t} e^{j\left(\sqrt{\omega_o^2 - \frac{\gamma^2}{4}}t + \phi\right)}$$

$$x(t) = Ae^{-\frac{\gamma}{2}t} \cos\left(\sqrt{\omega_o^2 - \frac{\gamma^2}{4}}t + \phi\right)$$



* amplitude *decays* due to damping

* frequency *reduced* due to damping

How damped?

Quality factor: unitless ratio of natural frequency to damping parameter

$$Q \equiv \frac{\omega_0}{\gamma}$$

Sometimes write solution in terms of ω_0 and Q

$$z(t) = A e^{-\frac{\omega_0}{2Q}t} e^{j\left(\omega_0 \sqrt{1 - \frac{1}{4Q^2}} t + \phi\right)}$$

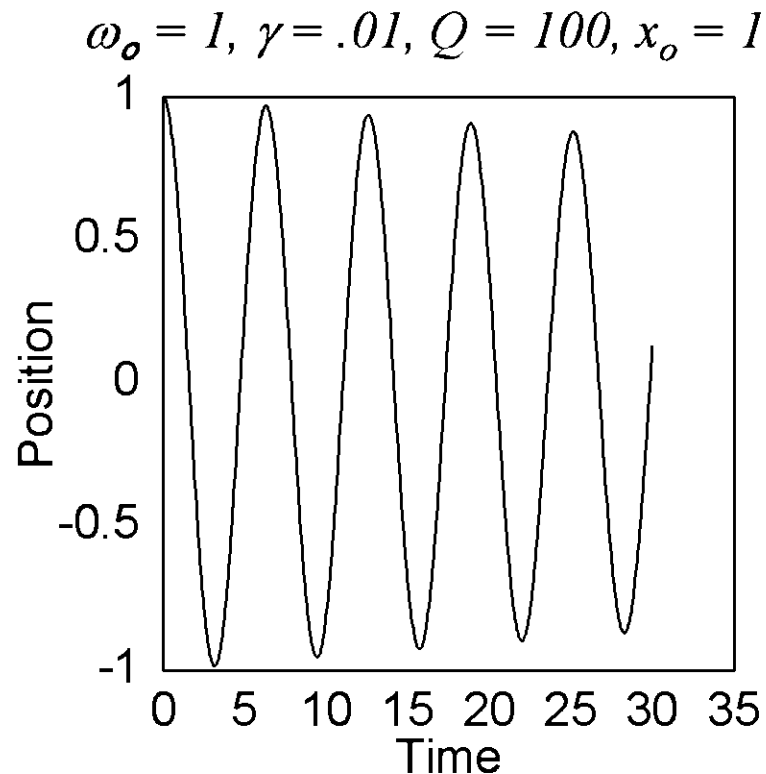
Sometimes write EOM in terms of ω_0 and Q :

$$\ddot{x} + \frac{\omega_0}{Q} \dot{x} + \omega_0^2 x = 0$$

1. "Under Damped" or "Lightly Damped": $Q \gg 1$

Oscillates at $\sim \omega_o$ (slightly less)

Looks like SHM (constant A) over a few cycles:



Amplitude drops by $1/e$ in Q/π cycles.

2. "Over Damped": $Q \ll 1 \quad \omega_o \ll \gamma$

$$z(t) = Ae^{-\frac{\gamma}{2}t} e^{j\left(\sqrt{\omega_o^2 - \frac{\gamma^2}{4}}t + \phi\right)}$$

→ imaginary!

$$z(t) = Ae^{-\frac{\gamma}{2}t} e^{j\left(j\sqrt{\frac{\gamma^2}{4} - \omega_o^2}t + \phi\right)}$$

$$z(t) = Ae^{-\frac{\gamma}{2}t} e^{-\sqrt{\frac{\gamma^2}{4} - \omega_o^2}t} e^{j\phi}$$

part of A

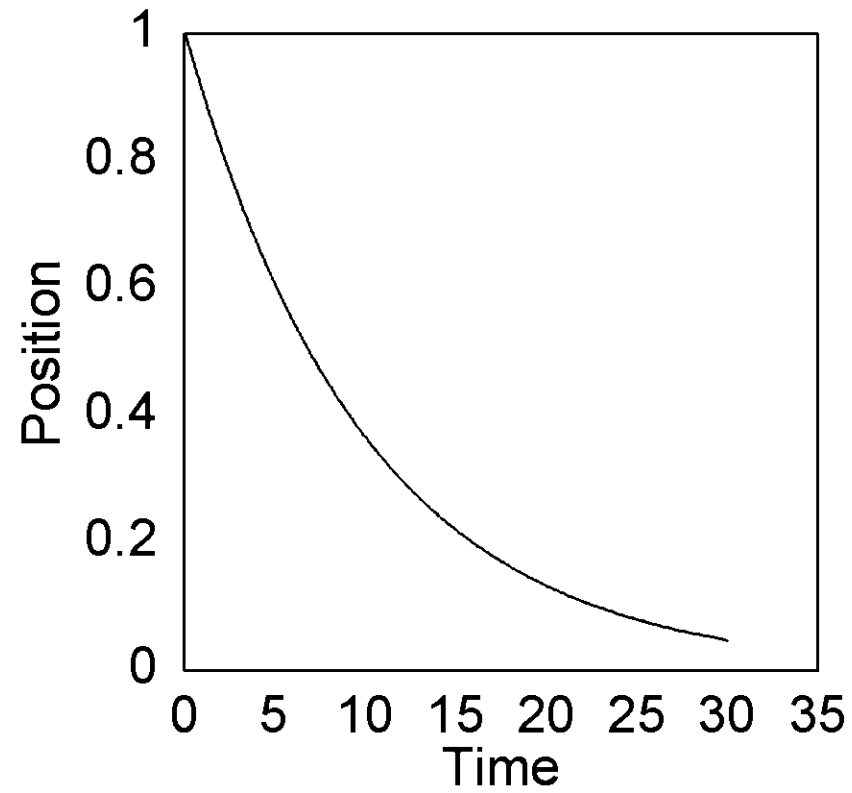
Still need two constants for the 2nd order EOM:

$$z(t) = A_1 e^{-\left(\frac{\gamma}{2} + \sqrt{\frac{\gamma^2}{4} - \omega_o^2}\right)t} + A_2 e^{-\left(\frac{\gamma}{2} - \sqrt{\frac{\gamma^2}{4} - \omega_o^2}\right)t}$$

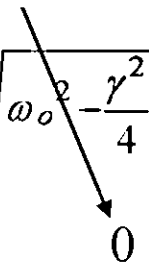
No oscillations!

Over Damped

$$\omega_o = 1, \gamma = 10, Q = .1, x_o = 1$$



3 "Critically Damped": $Q = 0.5$ $\gamma = 2\omega_o$

$$z(t) = Ae^{-\frac{\gamma}{2}t} e^{j\left(\sqrt{\omega_o^2 - \frac{\gamma^2}{4}}t + \phi\right)}$$


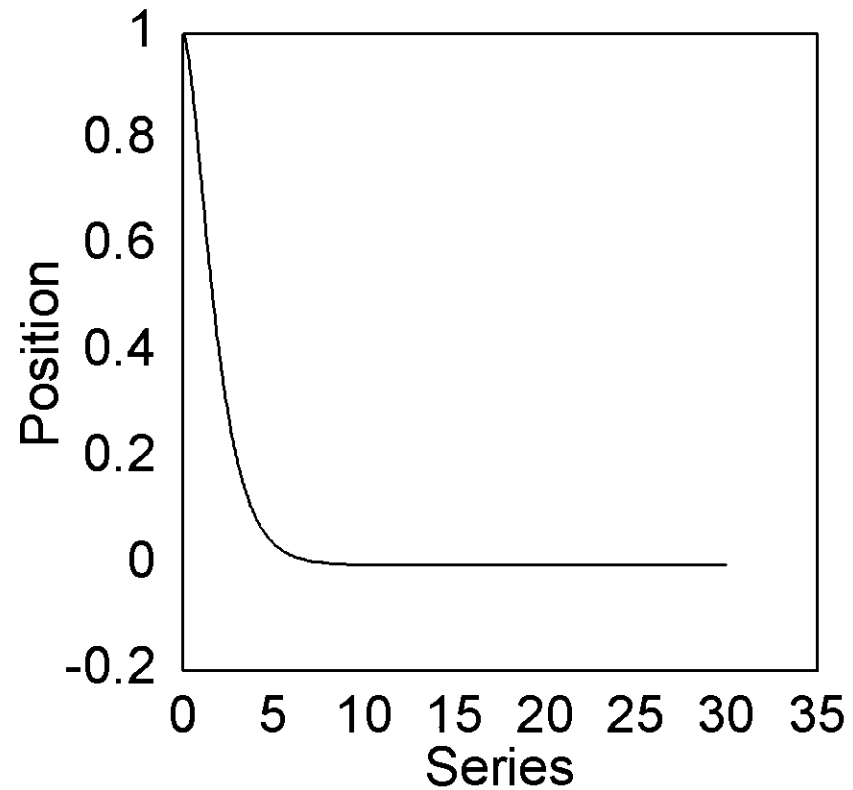
$$z(t) = (A_1 + A_2)e^{-\left(\frac{\gamma}{2}\right)t}$$

...really just one constant, and we need two. Real solution:

$$z(t) = (A + Bt)e^{-\left(\frac{\gamma}{2}\right)t}$$

Critically Damped

$$\omega_o = 1, \gamma = 2, Q = .5, x_o = 1$$



Fastest approach to zero with no overshoot.

Real oscillators lose energy due to damping. This can be represented by a damping force in the equation of motion, which leads to a decaying oscillation solution. The relative size of the resonant frequency and damping parameter define different behaviors: lightly damped, critically damped, or over damped.

